

Quarter Symmetric Connections On Complex Weyl Manifolds

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Abstract. In this work, we study quarter symmetric linear connections on Kähler Weyl manifolds and almost contact Weyl manifolds.

Keywords. Weyl manifold · Kähler Weyl manifold · Almost contact Weyl manifold · Quarter symmetric linear connection.

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1 INTRODUCTION

A gauge invariant theory which unifies the gravity and the electromagnetic fields was first introduced by Weyl in 1918 [13]. For physical reasons, his theory was not accepted but it remained both as a part of physics and mathematics. Weyl manifold is a differentiable manifold with a torsion free connection which is non-metric.

In 1924, Friedmann and Schouten introduced a semi-symmetric linear connection in a differentiable manifold [4]. After that, in 1932, Hayden introduced the notion of metric connection with torsion in a Riemannian manifold [6]. Moreover, Yano studied semi-symmetric metric connection in a Riemannian manifold and obtained a result about conformally flatness [14].

The notion of semi symmetric connection was generalized to quarter symmetric connection by Golab in 1975 [5]. There are many papers about quarter symmetric connection not only in Riemannian manifolds but also in Hermitian, Kähler, Kenmotsu manifolds (see Mishra and Pandey [9], Dwivedi [3], Pusic [12], Yano and Imai [15]).

In this work, we consider a quarter symmetric connection on Kähler Weyl manifolds and almost contact Weyl manifolds and examine the properties of this connection.

2 PRELIMINARIES

A Weyl manifold is a differentiable manifold M of dimension n with a conformal metric tensor g and a symmetric connection D which satisfies, called the

compatibility condition,

$$D_k g_{ij} = 2\omega_k g_{ij}, \quad (2.1)$$

where ω is a 1-form. Such a Weyl manifold is denoted by $M_n(g, \omega)$. If ω is a closed form, $M_n(g, \omega)$ is conformal to a Riemannian manifold.

Under the conformal change of the metric tensor g ,

$$\check{g}_{ij} = \lambda^2 g_{ij}, \quad \lambda > 0, \quad (2.2)$$

the 1-form ω changes by the law

$$\check{\omega}_k = \omega_k + D_k \ln \lambda. \quad (2.3)$$

A quantity S is called a satellite of g with weight r if it admits a transformation of the form

$$\check{S} = \lambda^r S, \quad (2.4)$$

under the change (2.2) of the metric tensor g .

The prolonged (extended) covariant derivative of a satellite S of weight r is defined by

$$\dot{D}_k S = D_k S - r \omega_k S, \quad (2.5)$$

from which it follows that $\dot{D}_k g_{ij} = 0$ (see [16], [7], [10]).

It is easy to see from (2.1) that

$$\Gamma_{kl}^i = \left\{ \begin{matrix} i \\ kl \end{matrix} \right\} - g^{im} (g_{mk} \omega_l + g_{ml} \omega_k - g_{kl} \omega_m), \quad (2.6)$$

where Γ_{jk}^i are the coefficients of the Weyl connection D and $\left\{ \begin{matrix} i \\ kl \end{matrix} \right\}$ are the connection coefficients of the Levi-Civita connection.

The mixed curvature tensor, the covariant curvature tensor, the Ricci tensor and the scalar curvature for $M_n(g, \omega)$ are respectively given by [11]:

$$v^j W_{jkl}^p = (D_k D_l - D_l D_k) v^p, \quad (2.7)$$

$$W_{h jkl} = g_{hp} W_{jkl}^p, \quad (2.8)$$

$$W_{ij} = W_{ijp}^p = g^{hk} W_{hijk}, \quad (2.9)$$

$$s = g^{ij} W_{ij}. \quad (2.10)$$

By considering (2.7), the explicit form of the mixed curvature tensor W_{jkl}^p for $M_n(g, \omega)$ is

$$W_{jkl}^p = \partial_k \Gamma_{jl}^p - \partial_l \Gamma_{jk}^p + \Gamma_{hk}^p \Gamma_{jl}^h - \Gamma_{hl}^p \Gamma_{jk}^h. \quad (2.11)$$

The mixed curvature tensor, the covariant curvature tensor and the Ricci tensor of $M_n(g, \omega)$ satisfy the following properties [11]:

$$W_{ijkl} + W_{ijlk} = 0, \quad W_{ikl}^i = n(D_l \omega_k - D_k \omega_l) = 2n D_{[l} \omega_{k]}, \quad (2.12)$$

$$W_{ijkl} + W_{jikl} = 4g_{ij} D_{[l} \omega_{k]}, \quad W_{[ij]} = n D_{[i} \omega_{j]}. \quad (2.13)$$

Let N be an n -dimensional Riemannian manifold endowed with a linear connection ∇ . Then ∇ is said to be quarter symmetric if the torsion tensor T_{jk}^i of ∇ satisfies

$$T_{jk}^i = p_j A_k^i - p_k A_j^i, \quad (2.14)$$

where p_k is a 1-form and A_i^j is any $(1,1)$ tensor field. If A_{jk} is defined as $A_j^i g_{ik} = A_{jk}$, then

$$A_{jk} = U_{jk} + V_{jk}, \quad (2.15)$$

where U_{jk} and V_{jk} are respectively symmetric and anti symmetric part of A_{jk} [15].

3 KÄHLER WEYL MANIFOLDS

A Weyl manifold of dimension $2n$ is called Kähler Weyl if

$$F_j^i F_i^h = -\delta_j^h, \quad (3.1)$$

$$F_j^t F_i^s g_{ts} = g_{ji}, \quad (3.2)$$

and

$$\dot{D}_j F_i^k = 0, \quad \forall i, j, k, \quad (3.3)$$

where F_i^j is a $(1,1)$ tensor field of weight zero and called an almost complex structure, g_{ij} is Hermitian metric. Such a manifold will be denoted by $KM_{2n}(g, \omega)$ [2].

The $(0,2)$ tensor field F_{ij} of weight 2 and $(2,0)$ tensor field F^{ij} of weight -2 are, respectively, given by

$$F_{ij} = F_i^k g_{kj} = -F_{ji} \quad (3.4)$$

and

$$F^{ij} = F_k^j g^{ik} = -F^{ji}. \quad (3.5)$$

The contraction of (3.4) on the indices k and i gives $F_i^i = 0$.

Suppose that a Kähler Weyl manifold admits a quarter symmetric linear connection \bar{D} with the torsion tensor \bar{T} and satisfies the following compatibility condition

$$\bar{D}_k g_{ij} = 2\omega_k g_{ij}. \quad (3.6)$$

If we take $U_{jk} = g_{jk}$ and $V_{jk} = F_{jk}$ in (2.15), then we find that $A_k^i = \delta_k^i + F_j^i$. Therefore, the torsion tensor \bar{T} takes the form

$$\bar{T}_{jk}^i = p_j (\delta_k^i + F_k^i) - p_k (\delta_j^i + F_j^i). \quad (3.7)$$

We note that the 1-form p_k is of zero weight.

Theorem 3.1. *On every Kähler Weyl manifold there exists a unique quarter symmetric linear connection associated to every 1-form p and $(1,1)$ tensor field F .*

Proof. Assume that the relation between $\bar{\Gamma}_{mk}^j$ and Γ_{mk}^j is given by

$$\bar{\Gamma}_{mk}^j = \Gamma_{mk}^j + U_{mk}^j, \quad (3.8)$$

where $\bar{\Gamma}_{mk}^j$ and Γ_{mk}^j are respectively the coefficients of \bar{D} and D , and U_{mk}^j is any (1,2) tensor field. Then from (2.1), (3.6) and (3.8), we find that

$$U_{ik}^h g_{hj} + U_{jk}^h g_{hi} = 0. \quad (3.9)$$

After permuting the indices i, j and k in the above equation cyclicly and using some algebraic operations, we obtain

$$\begin{aligned} (U_{ik}^h + U_{ki}^h)g_{hj} &= (U_{ij}^h - U_{ji}^h)g_{hk} + (U_{kj}^h - U_{jk}^h)g_{hi} \\ &= \bar{T}_{ij}^h g_{hk} + \bar{T}_{kj}^h g_{hi}. \end{aligned} \quad (3.10)$$

From (3.7) and after some simplifications, we have

$$U_{ik}^t + U_{ki}^t = p_i (\delta_k^t - F_k^t) + p_k (\delta_i^t - F_i^t) - 2p^t g_{ik}, \quad (3.11)$$

where $p^t = p_k g^{tk}$. Since $\bar{T}_{ik}^t = U_{ik}^t - U_{ki}^t$, by considering the above equation, we obtain

$$U_{ik}^t = p_i \delta_k^t - p_k F_i^t - p^t g_{ik}. \quad (3.12)$$

Hence, we find that $\bar{\Gamma}_{mk}^j = \Gamma_{mk}^j + p_m \delta_k^j - p_k F_m^j - p^j g_{mk}$ which completes the proof. \square

The mixed curvature tensor \bar{W}_{jkl}^i for \bar{D} is given by

$$\bar{W}_{jkl}^i = \partial_k \bar{\Gamma}_{jl}^i - \partial_l \bar{\Gamma}_{jk}^i + \bar{\Gamma}_{jl}^m \bar{\Gamma}_{mk}^i - \bar{\Gamma}_{jk}^m \bar{\Gamma}_{ml}^i. \quad (3.13)$$

Hence, by considering the definition of $\bar{\Gamma}_{jl}^i$ and after a long straightforward calculations, we obtain

$$\begin{aligned} \bar{W}_{jkl}^i &= W_{jkl}^i + \delta_i^i \alpha_{jk} - \delta_k^i \alpha_{jl} + g_{jk} g^{it} \alpha_{tl} - g_{jl} g^{it} \alpha_{tk} - 2F_j^i \dot{D}_{[k} p_{l]} \\ &+ p^i (F_{jk} p_l - F_{jl} p_k) + p_j (F_k^i p_l - F_l^i p_k), \end{aligned} \quad (3.14)$$

where $\alpha_{jk} = \dot{D}_k p_j - p_j p_k + F_j^m p_m p_k + \frac{1}{2} g_{jk} p^m p_m$.

Therefore, the covariant curvature tensor \bar{W}_{ijkl} , the Ricci tensor \bar{W}_{jk} and the scalar curvature \bar{s} are respectively given by

$$\begin{aligned} \bar{W}_{ijkl} &= W_{ijkl} + g_{il} \alpha_{jk} - g_{ik} \alpha_{jl} + g_{jk} \alpha_{il} - g_{jl} \alpha_{ik} + 2F_{ij} \dot{D}_{[k} p_{l]} \\ &+ p_i (F_{jk} p_l - F_{jl} p_k) + p_j (F_{il} p_k - F_{ik} p_l), \end{aligned} \quad (3.15)$$

$$\begin{aligned} \bar{W}_{jk} &= W_{jk} + (n-2) \alpha_{jk} + g_{jk} g^{il} \alpha_{il} - g_{jl} \alpha_{ik} + 2g^{il} F_{ij} \dot{D}_{[k} p_{l]} \\ &+ F_{jk} p_l p^l - F_{jl} p^l p_k - F_{lk} p^l p_j, \end{aligned} \quad (3.16)$$

and

$$\bar{s} = s + 2(n-1) g^{jk} \alpha_{jk} + 2F^{lk} \dot{D}_{[k} p_{l]}. \quad (3.17)$$

Proposition 3.2. *The mixed curvature tensor \bar{W}_{ikl}^i and the covariant curvature tensor \bar{W}_{ijkl} of a Kähler Weyl manifold with a quarter symmetric linear connection satisfy the following relations:*

- (i) $\bar{W}_{ijkl} + \bar{W}_{ijlk} = 0$
- (ii) $\bar{W}_{ijkl} + \bar{W}_{jikl} = 4g_{ij}D_{[l}\omega_k]$
- (iii) $\bar{W}_{ikl}^i = W_{ikl}^i = 2nD_{[l}\omega_k]$.

Proof. (i) The covariant curvature tensor \bar{W}_{ijkl} of a Kähler Weyl manifold endowed with a quarter symmetric linear connection \bar{D} is given by (3.15). By changing the indices k and l and then taking the sum of the equations obtained gives $\bar{W}_{ijkl} + \bar{W}_{ijlk} = W_{ijkl} + W_{ijlk} = 0$.

(ii) Similarly, if we change the indices k and l in (3.15) and sum up the obtained equations, then we get $\bar{W}_{ijkl} + \bar{W}_{jikl} = W_{ijkl} + W_{jikl} = 4g_{ij}D_{[l}\omega_k]$.

(iii) Since $F_i^i = 0$, the result follows easily from (3.14). \square

Theorem 3.3. *If the curvature tensor of a Kähler Weyl manifold with a quarter symmetric linear connection vanishes and the 1-form p_k is locally a gradient, then the connection reduces to the Weyl connection.*

Proof. If $\bar{W}_{ijkl} = 0$ and the 1-form p_k is locally a gradient, then (3.15) takes the form

$$\begin{aligned} W_{ijkl} &= -g_{il}\alpha_{jk} + g_{ik}\alpha_{jl} - g_{jk}\alpha_{il} + g_{jl}\alpha_{ik} \\ &- p_i(F_{jk}p_l - F_{jl}p_k) - p_j(F_{il}p_k - F_{ik}p_l). \end{aligned} \quad (3.18)$$

If we permute the indices j , k and l in (3.18) cyclicly, then we obtain two more equations. Now, by taking the sum of the three equations and taking into account of the 1st Bianchi Identity for Weyl manifolds, we obtain

$$0 = g_{il}\alpha_{[jk]} + g_{ij}\alpha_{[kl]} + g_{ik}\alpha_{[lj]} + F_{jk}p_i p_l + F_{kl}p_i p_j + F_{lj}p_i p_k. \quad (3.19)$$

By contracting the above equation with $F^{jl}g^{ik}$, we get for $n \neq 2$

$$F^{jl}\alpha_{[jl]} = -p^k p_k. \quad (3.20)$$

Since $\alpha_{[jl]} = \frac{1}{2}(F_{jm}p^m p_l - F_{lm}p^m p_j)$,

$$\begin{aligned} -p^k p_k &= \frac{1}{2}F^{jl}(F_{jm}p^m p_l - F_{lm}p^m p_j) \\ &= \frac{1}{2}(\delta_m^l p^m p_l + \delta_m^j p^m p_j) \\ &= p^k p_k, \end{aligned} \quad (3.21)$$

from which we find that $p_k = 0$ for positive definite metric tensors belonging to the conformal class. Now since $p_k = 0$, $\bar{\Gamma}_{mk}^j = \Gamma_{mk}^j + p_m \delta_k^j - p_k F_m^j - p^j g_{mk}$ takes the form $\bar{\Gamma}_{mk}^j = \Gamma_{mk}^j$ which completes the proof. \square

Let M_{2n+1} be a differentiable manifold of dimension $2n + 1$. An almost contact structure (ϕ, ξ, η) on M_{2n+1} is a triple satisfying the following relations

$$\phi_i^j \phi_j^k = -\delta_i^k + \eta_i \xi^k, \quad (4.1)$$

$$\eta_i \xi^i = 1, \quad (4.2)$$

$$\phi_i^j \xi^i = 0, \quad (4.3)$$

$$\eta_i \phi_j^i = 0, \quad (4.4)$$

where ϕ_i^j is a tensor field of type $(1, 1)$, ξ^i is a vector field and η_i is a 1-form. Moreover, if there is given a Riemannian metric g_{ij} such that

$$g_{ij} \phi_t^i \phi_s^j = g_{ts} - \eta_t \eta_s, \quad (4.5)$$

$$g_{ij} \xi^j = \eta_i, \quad (4.6)$$

then (ϕ, ξ, η, g) is called an almost contact metric structure on M . A differentiable manifold M_{2n+1} with almost contact metric structure (ϕ, ξ, η, g) is called almost contact metric manifold [1].

It is easy to see that the tensor ϕ_{ij} , which is defined by $\phi_i^k g_{jk} = \phi_{ij}$, is anti symmetric and contraction of ϕ_i^j gives $\phi_i^i = 0$.

It follows immediately from the equations (4.1), (4.2) and (4.5) that the $(1, 1)$ tensor field ϕ_i^j , the 1-form η_i and the vector field ξ^i are weight of 0, 1 and -1 , respectively.

Let $M_{2n+1}(g, \omega)$ be a Weyl manifold with the connection D . Then $M_{2n+1}(g, \omega)$ has an almost contact structure if the following conditions are satisfied in addition to the conditions (4.1)-(4.6) [8]:

$$\dot{D}_k g_{ij} = 0, \quad \dot{D}_k \phi_i^j = 0, \quad \dot{D}_k \eta_i = 0, \quad \dot{D}_k \xi^i = 0. \quad (4.7)$$

Such a manifold is called almost contact Weyl manifold and will be denoted by $ACM_{2n+1}(g, \omega)$.

Now, we consider the manifold $ACM_{2n+1}(g, \omega)$ with a quarter symmetric linear connection \tilde{D} and the torsion tensor \tilde{T} is of the form

$$\tilde{T}_{jk}^i = q_j \phi_k^i - q_k \phi_j^i, \quad (4.8)$$

where the $(1, 1)$ tensor field $A_i^j = \phi_i^j$ and the 1-form $q_j = f \eta_j$, where f is any function of weight -1 . Here, we also have

$$\tilde{D}_k g_{ij} = 2\omega_k g_{ij}. \quad (4.9)$$

Theorem 4.1. *On every almost contact Weyl manifold there exists a unique quarter symmetric linear connection associated to every 1-form q and $(1, 1)$ tensor field ϕ .*

Proof. Suppose that the relation between $\tilde{\Gamma}_{mk}^j$ and Γ_{mk}^j be

$$\tilde{\Gamma}_{mk}^j = \Gamma_{mk}^j + U_{mk}^j, \quad (4.10)$$

where $\tilde{\Gamma}_{mk}^j$ and Γ_{mk}^j are the coefficients of the connections \tilde{D} and D , respectively and U_{mk}^j is any tensor field of type $(1, 2)$.

From (2.1), (4.9) and (4.10) we have

$$U_{ik}^h g_{hj} + U_{jk}^h g_{hi} = 0. \quad (4.11)$$

Permuting cyclicly the indices i, j, k and after some modifications, we obtain

$$\begin{aligned} (U_{ik}^h + U_{ki}^h)g_{hj} &= (U_{ij}^h - U_{ji}^h)g_{hk} + (U_{kj}^h - U_{jk}^h)g_{hi} \\ &= \tilde{T}_{ij}^h g_{hk} + \tilde{T}_{kj}^h g_{hi} \end{aligned} \quad (4.12)$$

Using the definition of \tilde{T}_{ij}^h and after straightforward calculations, we find that

$$(U_{ik}^h + U_{ki}^h)g_{hj} = -q_i \phi_{kj} - q_k \phi_{ij}. \quad (4.13)$$

Multiplying the last equation by g^{jt} , we have

$$U_{ik}^t + U_{ki}^t = -q_i \phi_k^t - q_k \phi_i^t. \quad (4.14)$$

We conclude from the above equation that

$$\tilde{T}_{ij}^h = U_{ik}^t - U_{ki}^t = q_i \phi_k^t - q_k \phi_i^t. \quad (4.15)$$

Hence, we obtain

$$U_{ik}^t = -q_k \phi_i^t, \quad (4.16)$$

and therefore

$$\tilde{\Gamma}_{mk}^j = \Gamma_{mk}^j - q_k \phi_m^j. \quad (4.17)$$

□

The mixed curvature tensor for an almost contact Weyl manifold endowed with a quarter symmetric linear connection \tilde{D} is of the form

$$\tilde{W}_{jkl}^i = \partial_k \tilde{\Gamma}_{jl}^i - \partial_l \tilde{\Gamma}_{jk}^i + \tilde{\Gamma}_{jl}^m \tilde{\Gamma}_{mk}^i - \tilde{\Gamma}_{jk}^m \tilde{\Gamma}_{ml}^i. \quad (4.18)$$

By using (4.17) and (4.18) we have

$$\begin{aligned} \tilde{W}_{jkl}^i &= \partial_k (\Gamma_{jl}^i - q_l \phi_j^i) - \partial_l (\Gamma_{jk}^i - q_k \phi_j^i) \\ &+ (\Gamma_{jl}^m - q_l \phi_j^m) (\Gamma_{mk}^i - q_k \phi_m^i) - (\Gamma_{jk}^m - q_k \phi_j^m) (\Gamma_{ml}^i - q_l \phi_m^i) \\ &= W_{jkl}^i - \partial_k (q_l \phi_j^i) + \partial_l (q_k \phi_j^i) - q_k \Gamma_{jl}^m \phi_m^i - q_l \Gamma_{mk}^i \phi_j^m \\ &+ q_l q_k \phi_j^m \phi_m^i + q_l \Gamma_{jk}^m \phi_m^i + q_k \Gamma_{ml}^i \phi_j^m - q_k q_l \phi_j^m \phi_m^i \end{aligned} \quad (4.19)$$

After some simplifications we obtain

$$\begin{aligned}\widetilde{W}_{jkl}^i &= W_{jkl}^i + \phi_j^i (\partial_l q_k - \partial_k q_l) + q_k (\partial_l \phi_j^i - \Gamma_{jl}^m \phi_m^i + \Gamma_{ml}^i \phi_j^m) \\ &- q_l (\partial_k \phi_j^i - \Gamma_{jk}^m \phi_m^i + \Gamma_{mk}^i \phi_j^m).\end{aligned}\quad (4.20)$$

If we use the definition of prolonged covariant derivative for ϕ_j^i and η_k , then we get

$$\widetilde{W}_{jkl}^i = W_{jkl}^i + \phi_j^i (\dot{D}_l q_k - \dot{D}_k q_l) + q_k \dot{D}_l \phi_j^i - q_l \dot{D}_k \phi_j^i. \quad (4.21)$$

Since $\dot{D}_l \phi_j^i = 0$, we find that

$$\widetilde{W}_{jkl}^i = W_{jkl}^i + \phi_j^i (\dot{D}_l q_k - \dot{D}_k q_l). \quad (4.22)$$

From (4.22), the covariant curvature tensor \widetilde{W}_{ijkl} is given by

$$\widetilde{W}_{ijkl} = W_{ijkl} + 2\phi_{ji} \dot{D}_{[l} q_{k]}, \quad (4.23)$$

where $\dot{D}_{[l} q_{k]}$ is anti symmetric part of $\dot{D}_l q_k$.

Contracting the tensor \widetilde{W}_{jkl}^i with respect to i and l and using the fact that $\eta_i \phi_j^i = 0$, gives us

$$\widetilde{W}_{jk} = W_{jk} + \phi_j^i \dot{D}_i q_k. \quad (4.24)$$

Theorem 4.2. *For an almost contact Weyl manifold with a quarter symmetric linear connection, we have*

$$\widetilde{s} = s, \quad (4.25)$$

where \widetilde{s} and s are scalar curvature of the manifold with respect to the connections \widetilde{D} and D , respectively.

Proof. Multiplying (4.24) by g^{jk} and using the identity $\xi^j \phi_j^i = 0$ gives

$$\begin{aligned}\widetilde{s} &= s + \dot{D}_i (q_k g^{jk} \phi_j^i) \\ &= s + \dot{D}_i (f \eta_k g^{jk} \phi_j^i) \\ &= s + \dot{D}_i (f \xi^j \phi_j^i) \\ &= s.\end{aligned}$$

□

Theorem 4.3. *On an almost contact Weyl manifold with a quarter symmetric linear connection, if the 1-form q is locally a gradient, then*

$$\begin{aligned}\widetilde{W}_{jkl}^i &= W_{jkl}^i, \\ \widetilde{W}_{jk} &= W_{jk}.\end{aligned}$$

Proof. The proof is immediate from (4.22). □

Proposition 4.4. *On an almost contact Weyl manifold with a quarter symmetric connection, the following relations hold:*

$$(i) \quad \widetilde{W}_{ijkl} + \widetilde{W}_{ijlk} = 0$$

$$(ii) \quad \widetilde{W}_{ijkl} + \widetilde{W}_{jikl} = \frac{4}{n} g_{ij} W_{[lk]}$$

$$(iii) \quad \widetilde{W}_{ikl}^i = 2nD_{[l}\omega_{k]}$$

$$(iv) \quad \widetilde{W}_{klij} + \widetilde{W}_{kijl} + \widetilde{W}_{kjli} = 2 \left(\phi_{kl} \dot{D}_{[i} q_{j]} + \phi_{ki} \dot{D}_{[j} q_{l]} + \phi_{kj} \dot{D}_{[l} q_{i]} \right)$$

Proof. (i). Changing the indices k and l in (4.23) yields

$$\widetilde{W}_{ijlk} = W_{ijlk} - 2\phi_{ji} \dot{\nabla}_{[l} q_{k]}. \quad (4.26)$$

By adding (4.23) to (4.26) we obtain the result.

(ii). Similar to proof (i).

(iii). Contracting (4.22) with respect to i and j yields

$$\widetilde{W}_{ikl}^i = W_{ikl}^i + \phi_i^i \left(\dot{D}_l q_k - \dot{D}_k q_l \right). \quad (4.27)$$

Since $\phi_i^i = 0$, we find that

$$\widetilde{W}_{ikl}^i = W_{ikl}^i = 2nD_{[l}\omega_{k]}. \quad (4.28)$$

(iv). Using the 1st Bianchi Identity

$$W_{klij} + W_{kijl} + W_{kjli} = 0, \quad (4.29)$$

and after the straightforward calculations, we get the result. \square

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